

## Error of numerical derivation

1 I

$$f'(x) = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - f(x)}{\Delta x} \approx \frac{f(x+\Delta x) - f(x)}{\Delta x} = f'(x) + \frac{1}{2!} f''(x) \Delta x + \frac{1}{3!} f^{(3)}(x) \Delta x^2 + \dots$$

$$\text{Let } (D_{\Delta x} F)(x) = \frac{f(x+\Delta x) - f(x)}{\Delta x},$$

then  $\text{error}(\Delta x) = |(D_{\Delta x} F)(x) - f'(x)|$ . We expect  $\text{error}(\Delta x) = O(\Delta x^1)$ .

Error of the linear approximation:

big Oh:

$$c_2 \Delta x \leq \text{error}(\Delta x) \leq c_1 \Delta x$$

$c_1, c_2 > 0$ , for sufficiently small  $\Delta x$

$$|f(x+\Delta x) - [f(x) + f'(x)\Delta x]| \leq \frac{1}{2} \Delta x^2 \max_{s \in [x, x+\Delta x]} \|f''(s)\|$$

$$\text{So } \text{error}(\Delta x) \leq \frac{1}{2} \Delta x \max_{s \in [x, x+\Delta x]} \|f''(s)\| = O(\Delta x^1)$$

Numerical measurement of the exponent 1 in  $O(\Delta x^1)$

Set  $\Delta x_n = \frac{1}{2^n}$  (or to any  $\Delta x_n \rightarrow 0$  sequence, preferably  $\Delta x_n > 0$ )

If  $\text{error}(\Delta x) = C \cdot \Delta x^\alpha$ , then

$$\ln \text{error}(\Delta x) = \ln C \cdot \Delta x_n^\alpha = \ln C + \alpha \cdot \ln \Delta x_n = \ln C + \alpha \cdot \ln 2^{-n} = \ln C + \alpha \cdot \ln 2 \cdot (-n)$$

So plot the points  $(n, \ln(\text{error}(\Delta x_n)))$ . Fit a straight line to it

(this is called linear regression), find its slope  $m$  then  $\alpha = -\frac{m}{\ln 2}$ .

This is a log-log plot: similar to  $\ln \Delta x \leftrightarrow \ln(\text{error}(\Delta x))$ .

Numerical computation: assume float = 32 bit numbers.

$\Delta x$  smaller  $\rightarrow$  error is better. But: what if  $\Delta x = 2^{-30}$ ?

$$\text{Then } \frac{f(x+\Delta x) - f(x)}{\Delta x} \sim \frac{\underbrace{00\dots00100}_{32 \text{ digits}}}{\underbrace{00\dots0100}_{2 \text{ or } 3 \text{ nonzero digits}}} \sim \text{error's order} \sim 2^{-3} \sim 10\%, \text{ bad.}$$

Conclusion: pick  $n$  large enough, so  $\Delta x_n = \frac{1}{2^n}$  is small enough,

but do not pick too large  $n$ .

\* Probably it is better to make a  $\ln \Delta x_n \leftrightarrow \ln \text{error}(\Delta x_n)$  plot, so there will be no  $\ln 2$  factor.



# Estimation of the error of numerical derivatives

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$$(D_{\Delta x} f) = \frac{f(x+\Delta x) - f(x)}{\Delta x}, \quad |(D_{\Delta x} f)(x) - f'(x)| = \text{error}(\Delta x) \sim \Delta x^\alpha, \quad \alpha = 1$$

$$(\tilde{D}_{\Delta x} f) = \frac{f(x+\Delta x) - f(x-\Delta x)}{2\Delta x}, \quad \text{error}(\Delta x) \sim \Delta x^\alpha, \quad \alpha = 2$$

How can we guess  $\alpha$ ?

$$D_{\Delta x}: \frac{1}{\Delta x} \cdot \begin{array}{c} -1 \quad 1 \\ \bullet \quad \bullet \\ x \quad x+\Delta x \end{array}$$

$$\tilde{D}_{\Delta x}: \frac{1}{\Delta x} \cdot \begin{array}{c} -1/2 \quad 0 \quad 1/2 \\ \bullet \quad \bullet \quad \bullet \\ x-\Delta x \quad x \quad x+\Delta x \end{array}$$

- Check the equality  $(D_{\Delta x} f)(x) = f'(x)$  for  $x=0$ ,  $f(x) = 1, x, x^2, x^3, \dots, x^n, \dots$
  - Find the smallest  $n$  such that the equality fails.
- if  $D_{\Delta x}$  is independent on  $x$ , then shift  $x \rightarrow 0$ ,  $f(x) \rightarrow f(z+x)$

$$(D_{\Delta x} 1)(0) = \frac{1}{\Delta x} (1-1) = 0, \quad \text{same as } 1' \text{ at } x=0$$

$$(D_{\Delta x} x)(0) = \frac{1}{\Delta x} (\Delta x - 0) = 1, \quad \text{same as } x' = 1 \text{ at } x=0$$

$$(D_{\Delta x} x^2)(0) = \frac{1}{\Delta x} (\Delta x^2 - 0) = \Delta x \quad \text{not the same as } x^2 = 2x, \text{ which is } 0 \text{ at } x=0$$

$$\text{So } \text{error}(\Delta x) \sim \Delta x^1.$$

Now do the same for  $\tilde{D}_{\Delta x}$ !

$$(\tilde{D}_{\Delta x} 1)(0) = \frac{1}{\Delta x} \left( \frac{1}{2} \cdot 1 - \frac{1}{2} \cdot 1 \right) = 0 \quad \checkmark \quad \text{o.k.}$$

$$(\tilde{D}_{\Delta x} x)(0) = \frac{1}{\Delta x} \left( \frac{1}{2} \cdot \Delta x - \frac{1}{2} \cdot (-\Delta x) \right) = 1 \quad \checkmark \quad \text{o.k.}$$

$$(\tilde{D}_{\Delta x} x^2)(0) = \frac{1}{\Delta x} \left( \frac{1}{2} \Delta x^2 - \frac{1}{2} (-\Delta x)^2 \right) = 0 \quad \checkmark \quad \text{o.k.}$$

$$(\tilde{D}_{\Delta x} x^3)(0) = \frac{1}{\Delta x} \left( \frac{1}{2} \Delta x^3 - \frac{1}{2} (-\Delta x)^3 \right) = \Delta x^2 \quad \text{not zero: } (x^3)' = 2x^2, \text{ which is } 0 \text{ at } x=0$$

$$\text{So } \text{error}(\Delta x) \sim \Delta x^2$$

Exercise:

$$\textcircled{1} \text{ Repeat this for } \frac{d^3}{dx^3} \approx D_{\Delta x}^3 !$$

$$\textcircled{2} \text{ Repeat this for } \frac{d^3}{dx^3} \approx \tilde{D}_{\Delta x}^3 !$$

## Error of numerical solutions, ODE

$$\frac{d}{dt} \vec{y}(t) = \vec{f}(t, \vec{y}(t)),$$
$$\vec{y}(0) = \vec{y}_0.$$

1 II

① Euler's method:  $t_n = n \cdot \Delta t$ ,  $y(t_n) \approx y_n$

$$y_{n+1} = y_n + f(t_n, y_n) \Delta t$$

Euler's prediction of  $y_{n+1}$

② Heun's method:  $k_1 = f(t_n, y_n)$ ,  $k_2 = f(\underbrace{t_n + \Delta t}_{t_{n+1}}, y_n + f(t_n, y_n) \Delta t)$

$$y_{n+1} = y_n + \frac{k_1 + k_2}{2} \Delta t$$

③ Midpoint method:  $k = f(t_n + \frac{\Delta t}{2}, y_n + f(t_n, y_n) \frac{\Delta t}{2})$

$$y_{n+1} = y_n + k \Delta t.$$

Exercise: (a)  $\frac{d}{dt} y = \cos(t+y) \sin(y)$ ,  $y(0) = 2$ .

(b)  $\frac{d}{dt} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} y_1 - \cos(t) y_1 y_2 \\ -y_2 + \cos(t) y_1 y_2 \end{bmatrix}$ ,  $\vec{y}(0) = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$

Pick  $\Delta t = \frac{1}{8}, \frac{1}{16}, \dots, \frac{1}{2^N}$ ,  $N=15$ . Use Heun's and the midpoint methods, to calculate  $y(2)$  and  $\vec{y}(2)$ . Assume that  $\text{error}(\Delta t) \approx C \cdot \Delta t^\alpha$ .

Estimate  $C$  and  $\alpha$  for these methods. Which one is the better?

Repeat this for a pair of other ODE!

## Third order Runge-kutta

2II

Exercise: Design a third order Runge-kutta method!

(Hard with OCTAVE!)

Solution:

$$\begin{aligned} k_1 &= f(t_n, y_n) \\ \text{(draft)} \quad k_2 &= f(t_n + \alpha \Delta t, y_n + \beta \Delta t k_1) \\ k_3 &= f(t_n + \gamma \Delta t, y_n + \delta \Delta t k_1 + \varepsilon \Delta t k_2) \\ y_{n+1} &= y_n + (w_1 k_1 + w_2 k_2 + w_3 k_3) \Delta t \end{aligned}$$

Equations for  $\alpha, \beta, \gamma, \delta, \varepsilon, w_1, w_2, w_3$ :

- ①  $t_n$  can be set to 0.
- ②  $f(0 + \Delta u, y_n + \Delta v) \approx \sum_{\substack{r,s \geq 0 \\ r+s \leq 2}} \frac{f^{(r,s)}(0, y_n)}{r! s!} \Delta u^r \Delta v^s$  (Note that it is enough to expand  $f$  up to  $\Delta t^2$ , since in  $y_{n+1}$  it has an extra  $\Delta t$  multiplier)
- ③  $y_{n+1} \approx y(0 + \Delta t) \approx y(0) + y'(0) \Delta t + \frac{y''(0)}{2} \Delta t^2 + \frac{y'''(0)}{3} \Delta t^3$   
where  $y'(t) = f(t, y)$   
 $y''(t) = \left( \frac{\partial}{\partial t} + f(t, y) \frac{\partial}{\partial y} \right) f(t, y)$   
 $y'''(t) = \left( \frac{\partial}{\partial t} + f(t, y) \frac{\partial}{\partial y} \right)^2 f(t, y)$

- ④ Compare the predictions of  $y_{n+1}$ :  
③ and the method should give the same result up to a term  $o(\Delta t^4)$

Now we have a system of equations for  $\alpha, \dots, w_3$ .

- ⑤ Find a solution of those equations!
- ⑥ Check your method: Pick a DE, for example  $y' = \cos(t+y) \sin(y)$ ,  $y(0) = 2$ , and repeat the exercise of page 1II.

## Implicit Euler method

3 II

$$\vec{y}_{n+1} = \vec{y}_n + \Delta t \cdot \vec{f}(t_n + \Delta t, \vec{y}_{n+1}) \quad (\text{Compare to the explicit } \vec{y}_{n+1} = \vec{y}_n + \Delta t \cdot \vec{f}(t_n, \vec{y}_n))$$

equation for  $y_{n+1}$ . In practice, one solves it only approximately, in this exercise solve it "exactly".

$$\Delta t = \frac{1}{25}, \frac{1}{26}, \dots, \frac{1}{210}.$$

Exercise: Apply the explicit and implicit Euler methods for the following DE:

①  $y' = -y, \quad y(0) = 1, \quad y(2) = ?$

②  $y' = y, \quad y(0) = 1, \quad y(2) = ?$

③  $\frac{d}{dt} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & -1/2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}, \quad \vec{y}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \vec{y}(2) = ?$

④  $\frac{d}{dt} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} -y_1 + (y_1 y_2)^2 \\ +y_2 - (y_1 y_2)^2 \end{bmatrix}, \quad \vec{y}(0) = \begin{bmatrix} 1.5 \\ 1.3 \end{bmatrix}, \quad \vec{y}(2) = ?$

For ①, ②, ③ the equation for  $\vec{y}_{n+1}$  can be solved easily, so smaller  $\Delta t$  can be chosen, let say up to  $\Delta t = \frac{1}{215}$ .

In the case of ④, use a numerical solver for the computation of  $\vec{y}_{n+1}$ .

Which of the implicit and explicit methods is better?